

Content

| Course Code | Course Name | Semester | Theory | Practice | Lab | Credit | ECTS |
|-------------|-------------|----------|--------|----------|-----|--------|------|
| INF430 | Robotics | 7 | 3 | 0 | 0 | 3 | 4 |

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| Prerequisites | |
| Admission Requirements | |

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| Language of Instruction | |
| Course Type | Elective |
| Course Level | Bachelor Degree |
| Objective | The aim of the course on Robotics is to teach to the undergraduate students the fundemantals of the articulated robots, their components, and their structures. Kinematic modelling of the moving and articulated robots will be given. |
| Content | <ol style="list-style-type: none">1. Week: Robotic components : fundamental approaches2. Week: Forward kinematics : rotational matrix, rotational movement with respect to the local coordinate system, Euler angle, roll, pitch and yaw angles. An exapmle of 6 DoF robot.3. Week: Backward kinematics: solution, existencea and uniqueness of the solution4. Week: Translational motion5. Week: Dynamics of the robot joints and regulation: mathematical modelling6. Week: Working space and trajectory planning: basic presentation7. Week: vision-based sensing: introduction to image processing8. Week: midterm exam9. Week: Moving robots : trajectory following. Kinematics10. Week: Sensor technologies11. Week: Simulation and experimental study /Lego Mindstorm and Irobot programming12. Week: Simulation and experimental study /sensors13. Week: Simulation and experimental study /Programming and Robot intelligence14. Week: Simulation and experimental study, trajectory planning |
| References | <ol style="list-style-type: none">1) M.W. Spong, S.Hutchinson and M. Vidyasagar, "Robot Modeling and Control", Wiley, 2006.2) Phillip John McKerrow, "Introduction to Robotics", Addison-Wesley, 1991.3) Saeed B. Niku, "Introduction to Robotics. Analysis, Systems, Applications", Prentice Hall, 2001.4) Vladimir J. Lumelsky, "Sensing, Intelligence, Motion",Wiley, 2006.5) S. M. LaValle, " Planning Algorithms", Cambridge University Press, 2006. URL adresi http://planning.cs.uiuc.edu/.6) Mobile Robot Programming Toolkit (MRPT) (http://babel.isa.uma.es/mrpt/index.php/Main_Page)7) Player stage gazebo dökümantasyonu. Online URL adresi http://playerstage.sourceforge.net/ |

Theory Topics

| Week | Weekly Contents |
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